Finnish Meteorological Institute Russian Space Research Institute Lavochkin Association, Russia INTA, Spain

# **METNET**

The Next Generation Lander Mission For Martian Atmospheric Science Scientific Goals and Operations of the MetNet Precursor Mission W. Schmidt<sup>(1)</sup>, A.-M. Harri<sup>(1)</sup>, S. Alexashkin<sup>(3)</sup>, V. Linkin<sup>(2)</sup>, H. Guerrero<sup>(4)</sup>, K. Pichkadze<sup>(3)</sup>, L. Vázquez<sup>(5)</sup>, A. Lipatov<sup>(2)</sup>, M. Genzer<sup>(1)</sup>, M. Uspensky<sup>(1)</sup> and H. Haukka<sup>(1)</sup>

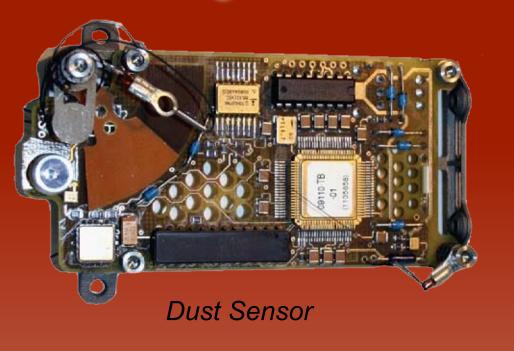
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## Mission Scientific Goals

With the help of the meteorological lander network the following scientific questions will be addressed:

Atmospheric dynamics and circulation
Surface to Atmosphere interactions and Planetary Boundary Layer
Dust raising mechanisms
Cycles of CO2, H2O and dust
Evolution of the Martian climate The Mars MetNet Precursor Mission (MMPM) is the technology demonstration project for the deployment of a larger network of small meteorological stations onto the surface of Mars. The development is done in collaboration between the Finnish Meteorological Institute (FMI), the Russian Lavoshkin Association (LA), the Russian Space Research Institute (IKI) and the Spanish National Institute for Aerospace Technology (INTA). The purpose of MMPM is to confirm the concept of deployment for the mini-meteorological stations onto the Martian surface, to get atmospheric data during the descent phase, and to get information about the meteorology and surface structure at the landing site from the meteorological station during

The understanding of these topics is important for the preparation of any future manned mission to Mars where reliable weather forecasts for the envisioned landing sites will be needed. The gained knowledge will also be important to understand





one Martian year or longer.

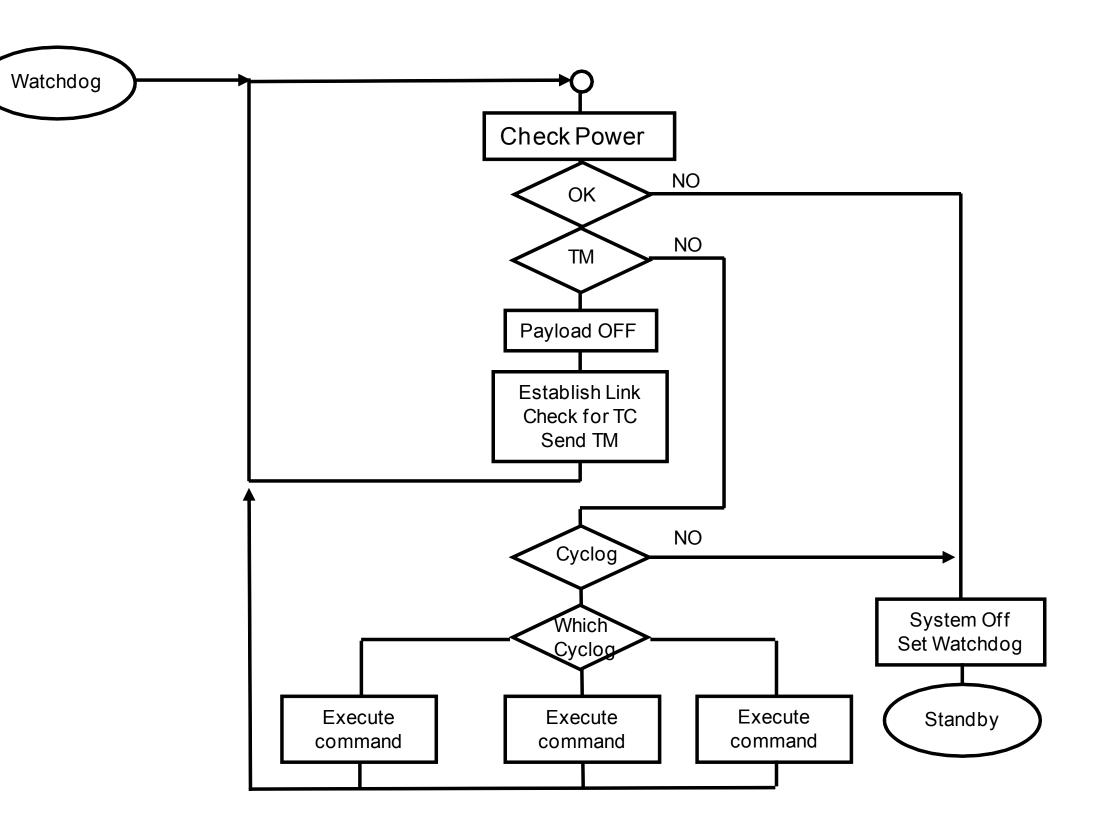
## **Operations** Concept

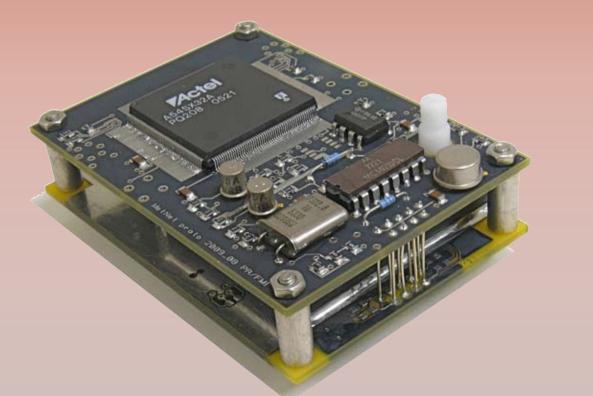
As there will be no or only limited commanding possibilities during the mission, the operations concept is based on an autonomous selection of different measurement scenarios, optimized for the local day – night cycle, telemetry and energy availability or special pre-programmed events.

#### Cyclogram control

As long as data storage and battery charge allow the instruments will be commanded according to a predefined command sequence stored as so called cyclogram, which is defined before launch or updated during the transfer phase. The operating system of the Lander will select one of several cyclograms depending on selection criteria which can be automatically adjusted during the mission. Implemented selection criteria are

• The absolute time as set before separation from the orbiter. This is used for Phobos eclipse meas-

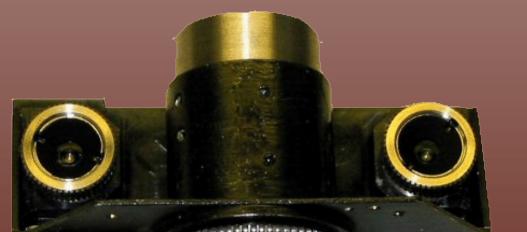




MetBaro Pressure Device



MetHumi Humidity Device



urements, when the shadow of the Martian moon moves across the landing site.

• Day/night calibration: using the MetSIS instrument around sunrise and sunset, the exact day/night cycle can be established and adjusted.

Mars MetNet Lander operations schematics.

- Day/night status: optical measurements with the camera or MetSIS are not useful during the night and will be skipped.
- Low battery status not allowing instrument operation with high energy demand like the PanCam.

Additionally the cyclogram interpreter contains the possibility to skip a command in case certain conditions are not met. This allows to utilize the same cyclogram structure even if an instrument should not be operated at the moment. This is the case if from the time of day and accelerometer-based impact angle measurement it can be deducted that the Dust Sensor is directly illuminated by the Sun, making infrared measurements impossible, or if previous operations indicated a severe failure.

#### Limiting Factors

In order to maximize the success possibilities for the landing of the semi-hard Lander, the precursor mission is aiming only at low altitude landing sites with high enough atmospheric pressure to support the aerobreaking unit. The envisaged equatorial descent insertion limits the possible latitude range to close to the equator. As the main goal for the precursor mission is the demonstration of the landing concept, some of the payload mass allocation was used to implement two additional beacons monitoring the separation and descent phase. Therefore the first mission does not include wind sensors or a LIDAR planned for the follow-up missions. As the unit is battery powered with flexible solar panels for re-charging, only a limited amount of energy is available for operating the instruments. Opposed to the RadioThermalGenerator (RTG)-powered American Viking Landers night operations of the pressure sensors will therefore be drastically limited. For future missions especially to higher altitudes and latitudes other options are under investigation.



Panoramic camera

Payload Instruments
Atmospheric Instruments
Pressure Device MetBaro (FMI)
Temperature Sensors (IKI)
Scientific Accelerometer (IKI)
Humidity Device MetHumi (FMI)







INTA

### **Optical Devices**

Panoramic Camera (IKI)
Solar Irradiance Sensor MetSIS (INTA) with Optical Wireless Link System OWLS
Dust Sensor, DS (INTA)

#### **Composition and Structure Devices**

- Tri-axial magnetometer MOURA (INTA)
- Scientific Accelerometer (IKI)

More information from the Mars MetNet Mission website http://metnet.fmi.fi Poster design: Harri Haukka, FMI